



GEFÖRDERT VOM

BETREUT VOM











Bundesministerium
für Bildung
und Forschung



Projektträger
Forschungszentrum
Karlsruhe (PTKA)

Modularization and Simulation-Based Optimization of Work Piece Handling in Manufacturing Cells

J. Fleischer, J. Wieser
wbk Institute of Production Science
Dept. of Mechanical Eng.
Universität Karlsruhe (TH)
Germany

Introduction
Simulation
Configurator


Outline

Introduction


Model modularization
for the simulation and
optimisation of agile
production systems

Conceptual design of
a simulation-based
configurator for
agile production systems

1. Initial Situation
2. Objective and Approach
3. Modularization
4. Simulation
5. Evaluation
6. Design of Configurator
7. Summary

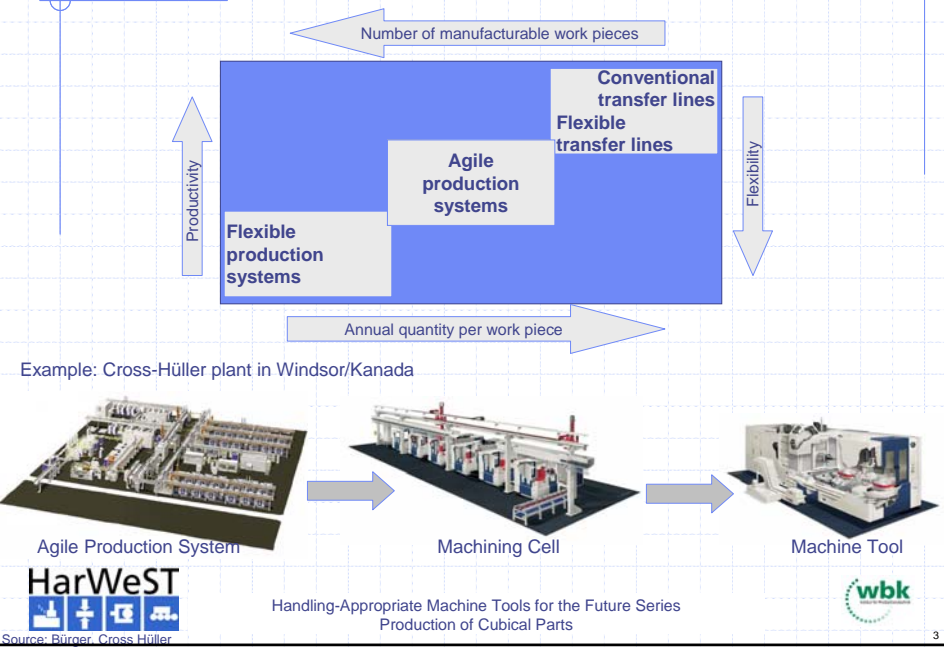


Handling-Appropriate Machine Tools for the Future Series
Production of Cubical Parts



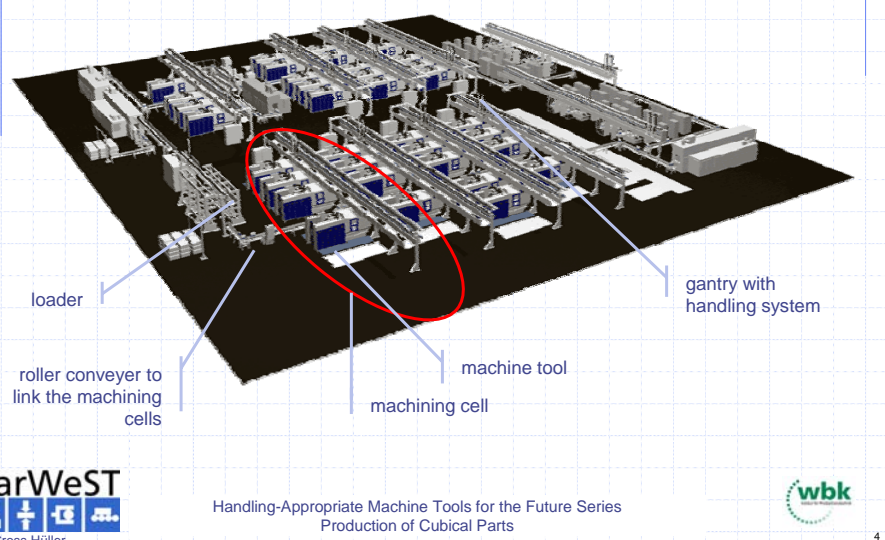
2

1. Overview of Production Systems



1. The Components of an Agile Production System

Agile production systems offer flexibility, high utilisation and high output.



Introduction Simulation Configurator

1. Initial Situation

linear module rectangular module split linear module circular module

Desired product

Architecture

Configuration of a suitable production system including components

Components

- lot size
- machining time
- costs
- quality
- ...

- machining centres
- belt conveyors
- handling systems
- clamping fixtures
- gantry loader
- ...

Shortcomings:

- non-holistic approach
- configuration is based on empirical values

HarWeST Handling-Appropriate Machine Tools for the Future Series Production of Cubical Parts wbk

5

Introduction Simulation Configurator

2. Objective

- Determination of the floor space arrangement (architecture) of the system
- Identification of the required capacity in terms of transport and handling systems
- Estimate of total system availability
- Use of synergy effects between machine tool and periphery

Holistic configuration of production systems on the basis of technical data

- Compliance with requirements through smaller system dimensions
→ **cost savings!**
- Shorter planning process for production systems
→ **time savings!**

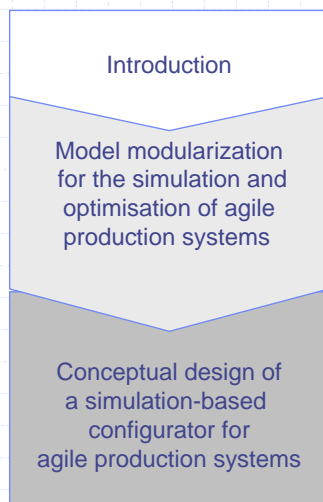
HarWeST Handling-Appropriate Machine Tools for the Future Series Production of Cubical Parts wbk

6

2. Approach

- Analysis and modularization of production systems
- Identification of the main influence parameters (architecture, machining time, production programme, transport performance*)
- Development of a modular simulation model
- Simulation, evaluation and optimisation of the utilisation and output of different production system configurations (statistical design of experiments, factorial design of experiments, systems theory approach)
- Determination of the required capacity in terms of transport and handling facilities under consideration of availability values
- Definition and weighting of criteria for the assessment of production systems
- Development of a system configurator for production systems on the basis of process simulation

Outline



1. Initial Situation

2. Objective and Approach

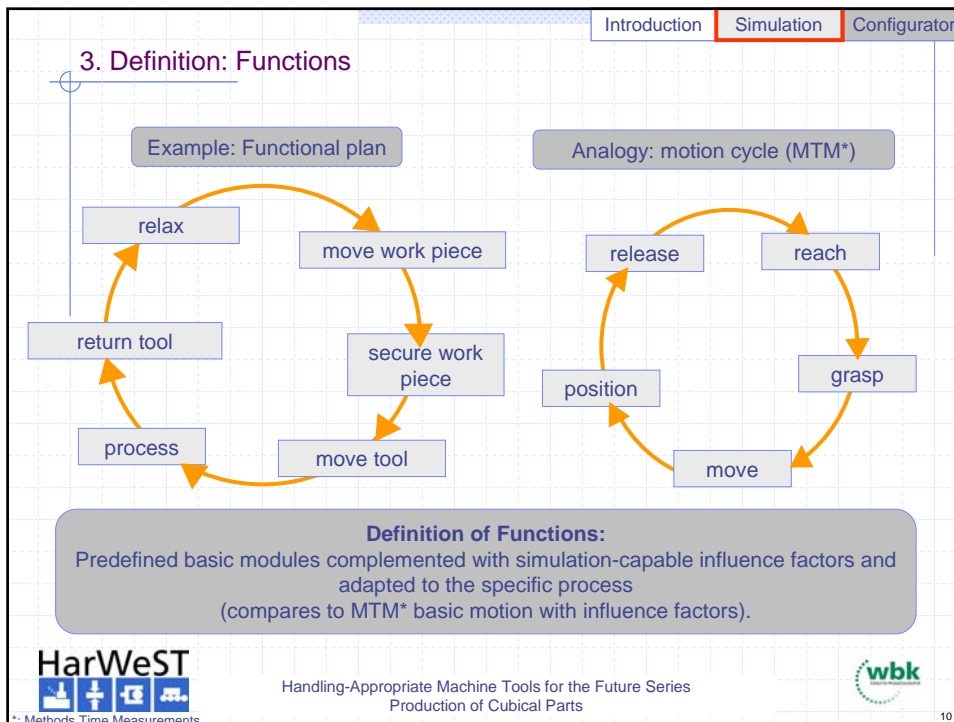
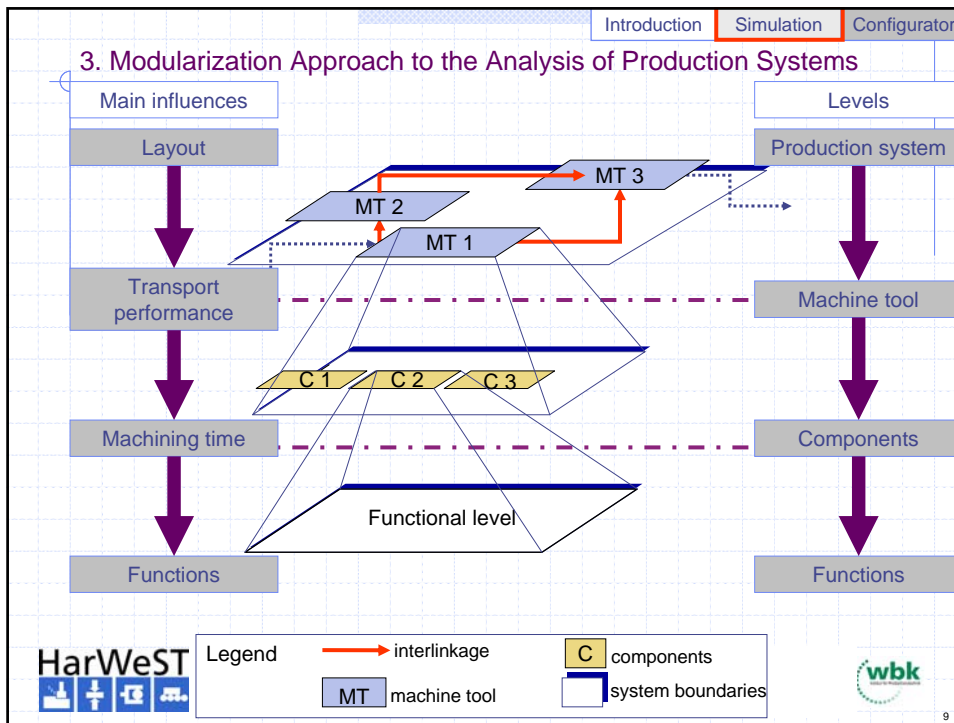
3. Modularization

4. Simulation

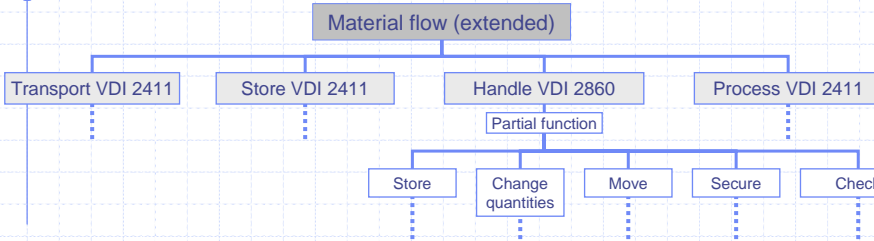
5. Evaluation

6. Design of Configurator

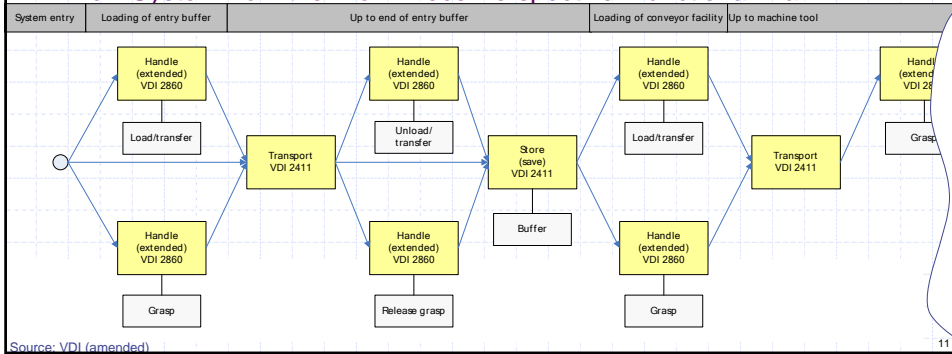
7. Summary



3. Material Flow/Functional Plan (Section)



Flow System from the Work Piece Perspective: Functional Plan



4. Modularization Transfer to the Simulation Model

Parameterisation of production systems

Identification of the model parameters on the basis of

Simulation.spp - eM-Plant 7.0 - [FlexCreator FlexModul Bericht]

Division of cells into

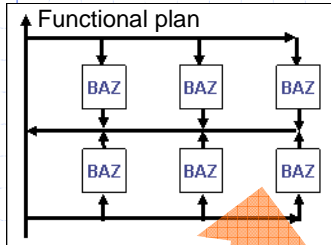
Grasp processes, Cell distances, Gantry parameters, OPs, ...

Simulation and readout of results

Compilation of an output report

for the Future Series
I Parts

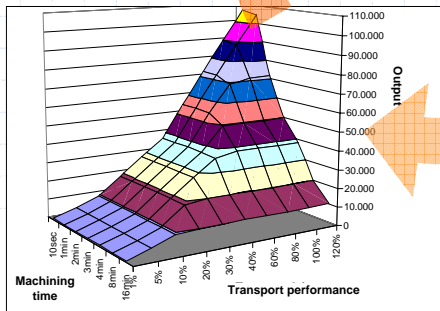
4. Simulation Overview



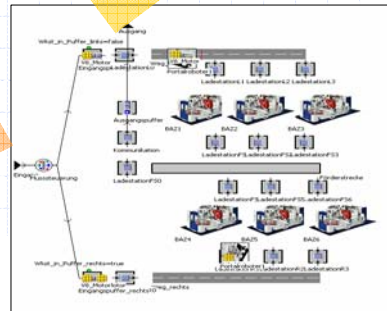
Input data

Down time, are caused at	Operational availability	MTRR	MTBF
Machining centre (at all modules)	95% →	9min 18sec	2h 56min 7sec
Gantry robot (at all modules)	97% ←	9min 17sec	5h 2min 46sec
Conveyor line (rectangular module only)	98% →	10min	8h 9min 9sec
Turntable (circular module only)	97% →	9min 17sec	5h 2min 46sec

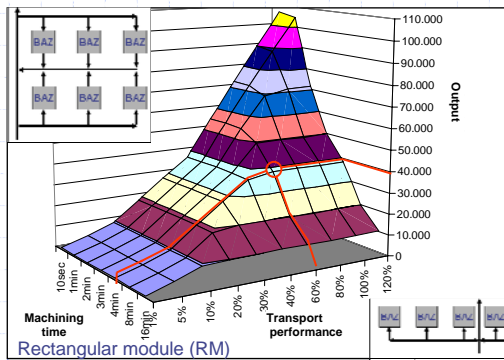
Results



Simulation



4. Results Rectangular and Split Linear Module (Section)

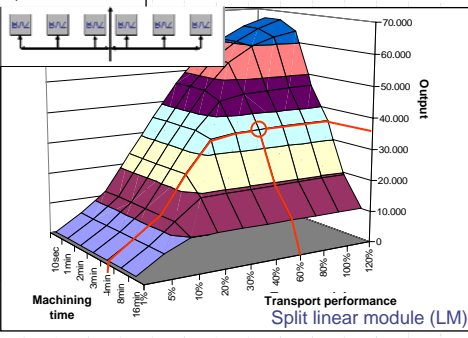


Example:

- simulation period: 21 days
- machining time: 4 min
- design: 6 MC per cell, modul comprises 3 cells
- transport performance*: 60 %
- output: approx. 36.000 (LM) or 38.000 (RM) respectively

Conclusion:

- The longer the machining time, the less significant the impact of the layout structure.
- The impact of transport performance* is lower than expected.
- An increase in machining time allows for transport performance* to be gradually reduced.



*: Combination of speeds and accelerations of gantry loader, belt conveyors, input and output buffers, cell interlinkage

5. Definition and Weighting of Evaluation Criteria

The project partners defined and evaluated the characteristics / criteria by means of paired comparison at the meeting held on October 19th 2004 at the Cross Hüller company in Ludwigsburg.
 Basis of evaluation : 0: column more important 1: column and row equally important 2: row more important

Characteristics/Criterion
Output
Utilisation
Investment costs
Operating cost
Floor space requirements
Volume flexibility/Expandability
Product flexibility
Development expenditure
Accessibility (tool change, setup)
Accessibility (safety)
Infrastructure, media supply
Leakproofness, chip transport, splash guard
Operational safety (operator exposure)
Total availability, backup strategy

First place: Accessibility, operational safety
 Third place: Output
 Fourth place: Total availability



Handling-Appropriate Machine Tools for the Future Series
 Production of Cubical Parts



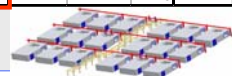
5. Cost/Benefit Analysis

Total (absolute): 3: better; 2: good; 1: limited; Max. sum (weighted): 30

Criteria	Weigh	Num.	Linear			Split linear			Rectangular			Circular			Maximum value
			Rating	Weigh	Num.	Rating	Weigh	Num.	Rating	Weigh	Num.	Rating	Weigh		
Output [units]	11%	73.470	2	0,22	73.778	2	0,22	76.038	3	0,33	73.686	2	0,22	3	
Utilisation [%]	10%	0.84	2	0,2	0.84	2	0,2	0.86	2	0,2	0.84	2	0,2	3	
Investment costs [€]	10%	7,50m	2	0,2	7,49m	2	0,2	8,41m	1	0,1	7,26m	1	0,1	3	
Operating costs [€]	7%							0			0			3	
Floor space requirement	4%	140	3	0,12	130	3	0,12	160	2	0,08	220	1	0,04	3	
Volume flexibility / Expandability	3%		3	0,09		3	0,09		3	0,09		1	0,03	3	
Product flexibility	4%		3	0,12		3	0,12		1	0,04		3	0,12	3	
Development expenditure	2%		3	0,06		3	0,06		1	0,02		1	0,02	3	
Accessibility (tool change/setup)	5%		3	0,15		3	0,15		2	0,1		1	0,05	3	
Accessibility (safety)	12%		3	0,36		3	0,36		2	0,24		1	0,12	3	
Infrastructure: media supply	3%		3	0,09		3	0,09		2	0,06		1	0,03	3	
Leakproofness, chip transport, splash guard	7%		3	0,21		3	0,21		2	0,14		1	0,07	3	
Operational safety (operator exposure)	12%		3	0,36		3	0,36		2	0,24		2	0,24	3	
Total availability, backup strategy	10%		2	0,2		3	0,3		3	0,3		2	0,2	3	
Total:				2,38			2,48			1,94			1,44		
Compliance:				79%			83%			65%			48%		
Rank:				2			1			3			4		



The split linear layout offers the greatest potential.



Introduction Simulation **Configurator**


Outline

Introduction


Model modularization
for the simulation and
optimisation of agile
production systems

Conceptual design of
a simulation-based
configurator for
agile production systems

1. Initial Situation
2. Objective and Approach
3. Modularization
4. Simulation
5. Evaluation
6. Design of Configurator
7. Summary



Handling-Appropriate Machine Tools for the Future Series
Production of Cubical Parts



17

Introduction Simulation **Configurator**

6. Overview of Configurator

Initial situation:

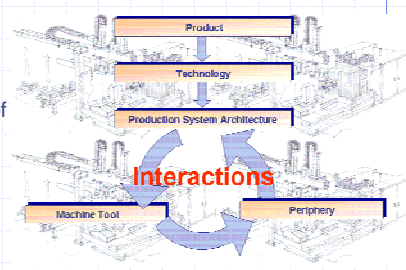
- Determination of the floor space arrangement “on paper” (mere planning)
- Required components are designed to maximum specifications
- An estimate of the availability and the potential impact of capacity bottlenecks is not possible

Objective:


- Development of a “system configurator“ for interlinked production systems on the basis of process simulation
- Optimum situation-specific selection of architecture, machine tool and periphery

Specific features:


- Clear and simple user prompting
- Parameter input and output via a standard software
- Automatic layout generation
- Automatic simulation
- Data structure generation
- Variable product, production and optimisation conditions



The diagram illustrates the interactions between five key components of a production system: Product, Technology, Production System Architecture, Machine Tool, and Periphery. These components are arranged in a circular fashion around a central point labeled 'Interactions'. Arrows indicate the flow and relationships between these elements, showing how they are interconnected and influence each other in the overall system design.



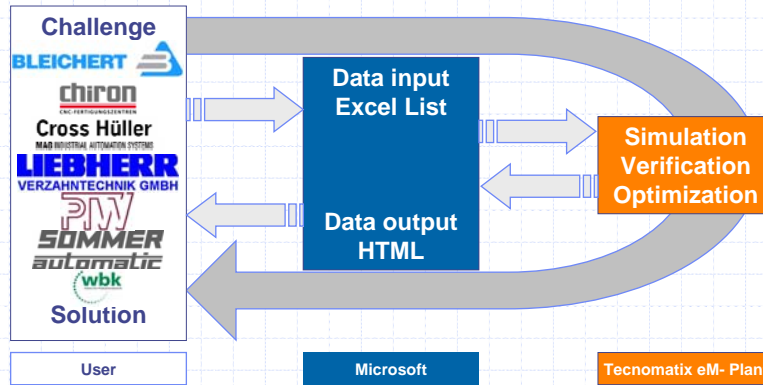
Handling-Appropriate Machine Tools for the Future Series
Production of Cubical Parts



18

6. Function Principle of the Configurator

The configurator algorithm comprises three stages:



6. Input (Selection)

The user can determine the production system parameters via Excel tables or chose from the library:

- Determination of operations (25 max.) with individual steps (20 max. each):
 - name of step
 - availability [%]
 - duration [sec]
- Cell design
 - position of entry conveyor [m]
 - position of exit conveyor [m]
 - Position of machining stations [m]
 - position of buffer [m]
 - allocation of operations to the different machining stations
 - distance between cells [m]
- Definition of sliding carriage:
 - acceleration [m/s²]
 - speed [m/s]
 - centre distance [mm]
- Gripper definitions (separate entry mask)

Dialog um Modul zu erstellen

OPs	einzelne Schritte der gewählten OP	Aufbau der gewählten Zelle				
	Bezeichnung (yyyyy)	Verfügbarkeit [%] (yy)	Dauer [s] (yy,xxx)	Zelle 1 Zelle 2 Zelle 3		
				Bezeichnung	Position [m]	OP
OP10				Eingangsband	3	0
OP20				Ausgangsband	6	40
OP30				MC_1	9	10
OP40				MC_2	12	10
OP50				MC_3	15	10
OP60				MC_4	18	15
OP70				MC_5	21	20
OP80				MC_6	24	20
OP90				MC_7	27	20
OP99				MC_8	30	25
				MC_9	33	30
				MC_10	36	30
				MC_11	39	30
				Gesamtlänge des Port	40	

Position Eingangsband [m]: 3 (yy,xx) Position Ausgangsband [m]: 6 (yy,xx)

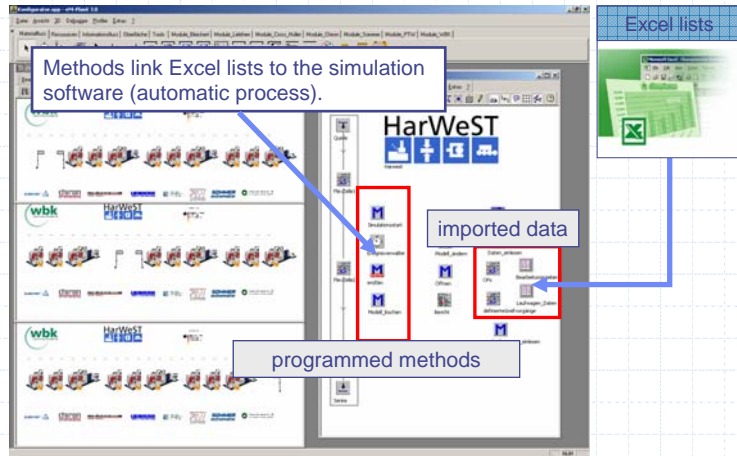
Zellenabstand: Abstand zwischen zwei Zellen [m]: 3 (yy,xx)

Daten der Laufwagen:

	Bezeichnung (yy,xx)	Geschwindigkeit [m/s] (yy)	Achsenabstand [mm] (yy)
Laufwagen 1	3,5	2	600
Laufwagen 2	3,5	2	600
Laufwagen 3	3,5	2	600

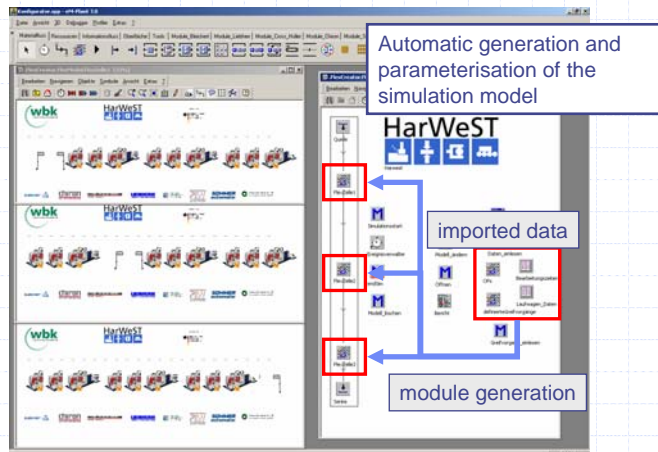
6. Setup of Simulation Model I/II

The architecture, the parameters and the detailed gripper processes are automatically transferred from the imported tables to the predefined method modules of the Tecnomatix eM-Plant process simulation software.

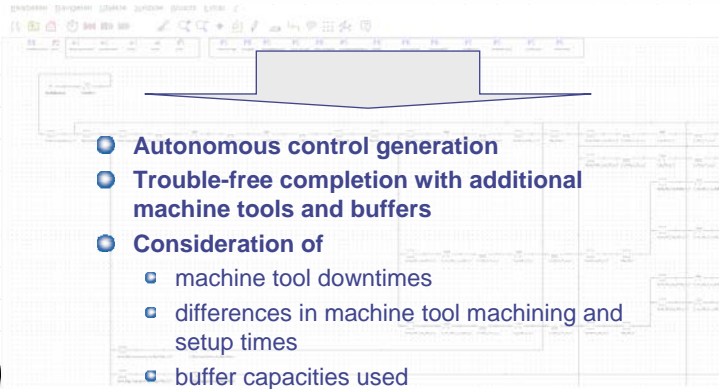


6. Setup of the Simulation Model II/II

The simulation model is automatically generated on the basis of the imported data.



6. Characteristics of a Production Cell



- **Autonomous control generation**
- **Trouble-free completion with additional machine tools and buffers**
- **Consideration of**
 - machine tool downtimes
 - differences in machine tool machining and setup times
 - buffer capacities used



7. Summary

Initial situation/Challenge

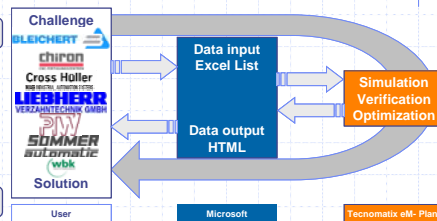
- Determination of the floor space arrangement "on paper" (mere planning process)
- Required components are designed to maximum specifications
- Estimate of availability and the potential impact of capacity bottlenecks (not always possible!)

Objective

- Design of a configurator for interlinked production systems on the basis of process simulation by taking a holistic approach

Result

- Conclusions on total system availability, impact of individual components
- User-oriented tool for easy compliance with specifications through „slower“ systems with smaller dimensions
 - **cost savings!**
- Shorter production system planning processes
 - **time savings!**



.... thank you for your attention!



wbk Institute of Production Science
Dept. of Mechanical Eng.
Universität Karlsruhe (TH)
Kaiserstrasse 12
76131 Karlsruhe, Germany
Tel. +49-721-608-6022
E-mail: wieser@wbk.uka.de
www.wbk-ka.de, www.harwest.de



Handling-Appropriate Machine Tools for the Future Series
Production of Cubical Parts

